User Interactivity

Nobody knows the kind of trouble we're in.
Nobody seems to think it all might happen again.
Gram Parsons, “One Hundred Years from Now”
Contents

Chapter Overview

Concepts

X3D Nodes and Examples

Chapter Summary and Suggested Exercises

Additional Resources and References
Chapter Overview
Overview: User Interactivity

User interactivity is initiated via sensor nodes, which capture user inputs and are hooked up to provide appropriate responses

- **TouchSensor** senses pointing device (mouse, etc.)
- **PlaneSensor** is a drag sensor that converts x-y pointer motion to move objects in a plane
- **CylinderSensor** and **SphereSensor** are drag sensors that convert x-y pointer motion to rotate objects
- **KeySensor** and **StringSensor** capture keyboard input

Interactivity sensors initiate animation chains
Related nodes

Chapter 4, Viewing and Navigation nodes
- Anchor: pointing device
  - Selects another Viewpoint or loads another scene
  - Show description when pointing device is over geometry
- Billboard rotates child geometry to face user
- Collision reports if viewer collides with geometry

Chapter 12, Environment Sensor and Sound
- LoadSensor reports when media asset is loaded
- ProximitySensor reports when user is in vicinity
- VisibilitySensor indicates when user's current camera view can see sensed geometry
Concepts
Importance of user interaction

Animated scenes are more interesting than static unchanging geometry

X3D interaction consists of sensing user actions and then prompting appropriate responses

Scenes that include behaviors which respond to user direction and control are more lively

Freedom of navigation and interaction contribute to user's sense of presence and immersion

Thus animation behaviors tend to be reactive and declarative, responding to the user
Sensors produce events

Sensors detect various kinds of user interaction and produce events to ROUTE within a scene

- Each sensor detects a certain kind of interaction, then produces one or more events

Authors decide how the events describing user interaction are interpreted and handled

- This approach allows great flexibility for authors
Using sensors in a scene

Three common design patterns (→ = ROUTE)

• Trigger (sensor) → Clock → Interpolator → Target node

• Sensor → Target node

• Sensor → Script (adaptor) → Target node
Pointing devices

Pointing device is primary tool for user interaction with geometry in a scene

• Mouse, Touchpad, touchscreen, or tracking stylus
• Arrow, Enter, other keys are allowed substitutes
• Trackball, data glove, game controller
• Tracking wand or other device in immersive 3D environments (such as a cave)
• Eye trackers and other advanced devices possible

X3D sensors designed for use with any generic pointing device, thus making scenes portable
Sensed geometry intersection, selection

Pointing devices communicate user's intended direction, movement, and selection (if any)
  • Browsers and viewers usually superimpose 2D icon to indicate user's intended pointing direction
  • 2D overlay icon may change to indicate selection

Sensors react to corresponding sibling and child geometry in the scene graph
  • Pointing at other geometry means sensor activation no longer possible
  • Usually one sensor must be deactivated before another can become active
Common field:  \textit{enabled}

\textit{enabled} is an inputOutput boolean field that turns a sensor node on or off

- Thus allowing author to permit or disable flow of user-driven events which drive other responses
- Set \textit{enabled}='false' to disrupt an event chain

Regardless of whether \textit{enabled}='true' a sensor still needs a ROUTE connection from its output, or else no interaction response occurs
Common field: *isOver*

`isOver` is an outputOnly boolean field that reports when pointing at sensed geometry

- `isOver` true value sent when pointer is over shapes
- `isOver` false value sent when pointer icon is no longer over shapes
- If selection occurred, `isOver` false doesn't occur until after selection is released

Routing `isOver` values can enable animation

- Rapid sequencing on/off might remain a difficulty
- Take care that animation doesn't move viewpoint or geometry out from under the pointing device
Common field: *isActive*

*isActive* is an outputOnly boolean field that reports when sensor has received user input

- *isActive* true value sent when selection begins
- *isActive* false value sent when selection released
- Note that *isActive* true already occurs as a prerequisite when a sensor is initially enabled

Routing *isActive* values can enable, disable TimeSensor and other animation nodes

- Rapid sequencing on/off can be a difficulty, however
- BooleanFilter, BooleanToggle, BooleanTrigger also useful: Chapter 9 Event Utilities and Scripting
Common field: *description*

Each sensor's *description* field alerts users to the presence and intended purpose of each sensor

- Thus including a *description* is quite important, otherwise user is left to guess about responses
- Nevertheless many authors forget to include *description*, which inhibits interactivity

X3D Specification gives browsers flexibility about how *description* strings are displayed

- Overlay text, window-border text, perhaps audio
Dragging

Dragging means to select (activate) a sensed object, then to move the pointing device while the sensor is still activated.

This user action causes continuous generation of output events while dragging motion occurs:

- Click + drag + release = Select + hold + release

Several common fields:

- enabled, description, isActive, isOver, touchTime

Three X3DDragSensorNode type sensors are:

- CylinderSensor, PlaneSensor, SphereSensor
3D (6DOF) control using 2D devices

Selected objects are 3D, located in 3D space
  • Which provides 6 degrees of freedom (DOF) for 3D object motion, e.g. \((x, y, z, \text{roll}, \text{pitch}, \text{yaw})\)

However most pointing devices only 2D control, since only movements are left-right, up-down
  • Mouse, touchpad or touch screen, keyboard, etc.

Must map 2D output device to 3D/6DOF motions
  • Each drag sensor thus defines how 2D motion is interpreted: surface of cylinder, plane, or sphere
  • Hopefully authored in a manner intuitive to user
X3D Nodes and Examples
TouchSensor node

TouchSensor affects adjacent geometry, provides basic pointing-device contact interaction

• Sends `isOver` true event when first pointed at
• Sends `isActive` true event when selected
• Sends `isActive` false event when deselected
• Sends `isOver` false event when no longer pointed at

Selection is deliberate action by user, for example

• Mouse, touchpad, touchscreen: left-click button
• Keyboard: `<Enter>` key
• 3D wand: selection button
Sensed geometry grouping

All geometry that is a peer (or children of peers) of the TouchSensor nodes can be sensed.

Use a grouping node (Group, Transform, etc.) to isolate sensed geometry of interest:

- Don't want to make entire scene selectable, otherwise interaction isn't very sophisticated.

Can attach different sensors to self-explanatory geometry for different tasks. Examples:

- Light switch `isOver` gives name, click to change.
- Billboarded Text or buttons for multiple controls.
Sensed geometry grouping

Separate sensed geometry from other shapes by using grouping nodes

Next slide shows example excerpt

- Chapter04-ViewingNavigation/BindOperations.x3d

Scene structure for this example

- Viewpoints consuming, producing events
- Display geometry, no sensor peer
- Selectable geometry, TouchSensor peer
- Regular animation design pattern: TimeSensor, Interpolator, target Script node, ROUTE connections
Chapter 4, BindOperations.x3d

Sensed group inside Transform node

Separate Group node

View #2

View #3

View #4

set_bind

-- The following advanced animation sequence uses nodes covered in Chapters 7, 8 and 9. -->

-- It does not need to be studied in this chapter. -->

<formField description='Open animation step choices here' fieldOfView='0.785' node='Clock' set_bind='true'/>

-- notice this next Viewpoint has been transformed with the text, so its position is relative -->

-- Text --

<.Text string="Click here to animate">
  <FontStyle justify="# MIDDLE" "BEGIN"/>
</Text>
</Shape>

-- Text --

<Shape>
  <Box size="7 1 0.02"/>
  <Appearance>
    <Material transparency="1"/>
  </Appearance>
</Shape>

-- Text --

<TouchSensor DEF='TextTouchSensor' description='Click to begin animating viewpoint selections' tNode='Clock'/>

-- Text --

<TimeSensor DEF='Clock' cycleInterval='10'/>

-- Text --

ROUTE fromField='touchTime' fromNode='TextTouchSensor' toField='set_startTime' toNode='Clock'/

-- Text --

ROUTE fromField='fraction_changed' fromNode='Clock' toField='set_fraction' toNode='TimingSequence'/

-- Text --

ROUTE fromField='bindView1' fromNode='TextTouchSensor' toField='set_bind' toNode='TimingSequence'/

ROUTE fromField='bindView2' fromNode='TextTouchSensor' toField='set_bind' toNode='TimingSequence'/

ROUTE fromField='bindView3' fromNode='TextTouchSensor' toField='set_bind' toNode='TimingSequence'//
Multiple TouchSensor nodes

Cannot sense just one part of grouped geometry
  • Unless split out as separate groups of geometry, then Transform-ed to look like single shape to user
Can use multiple TouchSensor nodes, ROUTEs and event chains to accomplish multiple tasks
Can DEF, USE copies of single TouchSensor node, allowing multiple shapes to trigger same action
If multiple TouchSensor nodes at same level or above a given piece of geometry, nearest wins
  • If tied at same distance, both activated at once
output event *touchTime*

*touchTime* sends an SFTime output event whenever sensed geometry is deselected

- Sent simultaneously with *isActive* false event

Three prerequisites must be met for *touchTime*:

1. Pointing device begins pointing at sensed geometry (generating *isOver* true event)
2. Pointing device is initially activated by user selection (generating *isActive* true event)
3. Pointing device is subsequently deactivated while still pointing at the sensed geometry (generating *isActive* false event)
output events \textit{hitPoint\_changed}, \textit{hitNormal\_changed}, \textit{hitTexCoord\_changed}

\textbf{hitPoint\_changed}

- sends output SFVec3f event providing 3D location coordinates of selection point, referenced to local coordinate system

\textbf{hitNormal\_changed}

- sends output SFVec3f event providing normal vector of underlying geometry at selection point

\textbf{hitTexCoord\_changed}

- sends output SFVec2f event providing 2D \((u, \nu)\) coordinates of underlying texture at selection point
<TouchSensor DEF='RunPump' description='touch to activate' enabled='true' />

<Shape>
  <Appearance DEF='pumpHouse'>
    <Material diffuseColor='0.82 0.78 0.74' />
    <IndexedFaceSet coordIndex='0 1 5 4 -1 5 1 2 6 -1 6 2 3 7 -1 3 0 4 7 -1 1 2 3 11 2' />
  </Appearance>
</Shape>
Example: opening doors

Interaction in 3D scenes doesn't always have to be literal. It is easier to click on a door to open it, rather than turning a door knob.

Next example compares TouchSensor selections

• Left door opens on initial selection (click)
• Right door opens on later deselection (unclick)

Key difference: *isActive* is first true, then false

• To fix: routing events through a BooleanFilter and TimeTrigger can initiate TimeSensor appropriately
• These are Event Utility nodes, covered in Chapter 9
<table>
<thead>
<tr>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>TouchSensor</td>
<td>Tracks location &amp; state of the pointing device, and detects when user points at geometry. Sensors are affected by peer nodes and children of peers.</td>
</tr>
<tr>
<td>DEF</td>
<td>[DEF ID #IMPLIED] DEF defines a unique ID name for this node, referencable by other nodes. <strong>Hint:</strong> descriptive DEF names improve clarity and help document a model.</td>
</tr>
<tr>
<td>USE</td>
<td>[USE IDREF #IMPLIED] USE means reuse an already DEF-ed node ID, ignoring <em>all</em> other attributes and children. <strong>Warning:</strong> do NOT include DEF (or any other attribute values) when using a USE attribute!</td>
</tr>
<tr>
<td>description</td>
<td>[description: accessType inputOutput, type SFString CDATA #IMPLIED] Text description to be displayed for action of this node. <strong>Hint:</strong> use spaces, make descriptions clear and readable.</td>
</tr>
<tr>
<td>enabled</td>
<td>[enabled: accessType inputOutput, type SFBbool (true</td>
</tr>
<tr>
<td>isActive</td>
<td>[isActive: accessType outputOnly, type SFBbool (true</td>
</tr>
<tr>
<td>isOver</td>
<td>[isOver: accessType outputOnly, type SFBbool (true</td>
</tr>
<tr>
<td>hitPoint_changed</td>
<td>[hitPoint_changed: accessType outputOnly, type SFVec3f CDATA #FIXED &quot;&quot;] Events containing 3D point on surface of underlying geometry, given in TouchSensor's local coordinate system.</td>
</tr>
<tr>
<td>hitNormal_changed</td>
<td>[hitNormal_changed: accessType outputOnly, type SFVec3f CDATA #FIXED &quot;&quot;] Events containing surface normal vector at the hitPoint.</td>
</tr>
<tr>
<td>hitTexCoord_changed</td>
<td>[hitTexCoord_changed: accessType outputOnly, type SFVec2f CDATA #FIXED &quot;&quot;] Events containing texture coordinates of surface at the hitPoint.</td>
</tr>
<tr>
<td>touchTime</td>
<td>[touchTime: accessType outputOnly, type SFTime CDATA &quot;0&quot;] Time event generated when sensor is touched by pointing device.</td>
</tr>
<tr>
<td>containerField</td>
<td>[containerField: NMTOKEN &quot;children&quot;] containerField is the field-label prefix indicating relationship to parent node. Examples: geometry Box, children Group, proxy Shape. containerField attribute is only supported in XML encoding of X3D scenes.</td>
</tr>
<tr>
<td>class</td>
<td>[class CDATA #IMPLIED] class is a space-separated list of classes, reserved for use by XML stylesheets. class attribute is only supported in XML encoding of X3D scenes.</td>
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</tbody>
</table>
PlaneSensor node

PlaneSensor converts x-y dragging motion by the pointing device into lateral translation in plane

- 2-tuple motion converted to 3-tuple SFVec3f
- Motion is parallel to local z=0 plane (screen plane)

Activated by peer geometry in scene graph

- Sensor itself is not rendered, unless background geometry or sensed shape itself has a planar side

Translation output values can follow a ROUTE connection to parent Transform translation

- Or connect to another SFVec3f field elsewhere
PlaneSensor fields, events

- Sends `isActive` true event when selected
- Sends `isActive` false event when deselected
- `minPosition`, `maxPosition` constrain X-Y translation to allowed planar region, defined as SFVec2f values
  - Example: `minPosition='-2 -2' maxPosition='2 2'`
- `offset` holds latest (or initial) SFVec3f position value
- `autoOffset='true'` remembers prior translation prior to resuming a new drag selection, otherwise `autoOffset='false'` jumps, restarts at initial position
- `translation_changed` and `trackPoint_changed` are the basic output events for sensor results
### TouchSensor

**TouchSensor** tracks location & state of the pointing device, and detects when user points at geometry.

**Hint:** Sensors are affected by peer nodes and children of peers.

#### DEF

<table>
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<tbody>
<tr>
<td>[DEF ID #IMPLIED]</td>
</tr>
<tr>
<td>DEF defines a unique ID name for this node, referencable by other nodes.</td>
</tr>
<tr>
<td><strong>Hint:</strong> Descriptive DEF names improve clarity and help document a model.</td>
</tr>
</tbody>
</table>

#### USE

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<th>Description</th>
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<tbody>
<tr>
<td>[USE IDREF #IMPLIED]</td>
</tr>
<tr>
<td>USE means reuse an already DEF-ed node ID, ignoring all other attributes and children.</td>
</tr>
<tr>
<td><strong>Hint:</strong> USEing other geometry (instead of duplicating nodes) can improve performance.</td>
</tr>
<tr>
<td><strong>Warning:</strong> do NOT include DEF (or any other attribute values) when using a USE attribute!</td>
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</table>

#### description

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<td><strong>Hint:</strong> Use spaces, make descriptions clear and readable.</td>
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<tr>
<td><strong>Hint:</strong> Many XML tools substitute XML character references automatically if needed (like '#38; for &amp; quot; for ' for ' for ').</td>
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</tbody>
</table>

#### enabled

<table>
<thead>
<tr>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[enabled: accessType inputOutput, type SFBool (true</td>
</tr>
<tr>
<td>Enables/disables node operation.</td>
</tr>
</tbody>
</table>

#### isActive

<table>
<thead>
<tr>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[isActive: accessType outputOnly, type SFBool (true</td>
</tr>
<tr>
<td>Click or move the mouse (pointer) to generate isActive events. Event isActive=true is sent when primary mouse button is pressed. Event isActive=false is sent when primary mouse button is released.</td>
</tr>
</tbody>
</table>

#### isOver

<table>
<thead>
<tr>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[isOver: accessType outputOnly, type SFBool (true</td>
</tr>
<tr>
<td>is pointing device over sensor's geometry?</td>
</tr>
</tbody>
</table>

#### hitPoint_changed

<table>
<thead>
<tr>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[hitPoint_changed: accessType outputOnly, type SFVec3f CDATA #FIXED '' ']</td>
</tr>
<tr>
<td>Events containing 3D point on surface of underlying geometry, given in TouchSensor's local coordinate system.</td>
</tr>
</tbody>
</table>

#### hitNormal_changed

<table>
<thead>
<tr>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[hitNormal_changed: accessType outputOnly, type SFVec3f CDATA #FIXED '' ']</td>
</tr>
<tr>
<td>Events containing surface normal vector at the hitPoint.</td>
</tr>
</tbody>
</table>

#### hitTexCoord_changed

<table>
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</tr>
</thead>
<tbody>
<tr>
<td>[hitTexCoord_changed: accessType outputOnly, type SFVec2f CDATA #FIXED '' ']</td>
</tr>
<tr>
<td>Events containing texture coordinates of surface at the hitPoint.</td>
</tr>
</tbody>
</table>

#### touchTime

<table>
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<tr>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[touchTime: accessType outputOnly, type SFTime CDATA '' '0']</td>
</tr>
<tr>
<td>Time event generated when sensor is touched by pointing device.</td>
</tr>
</tbody>
</table>

#### containerField

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<tr>
<th>Description</th>
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<td>[containerField: NMTOKEN 'children']</td>
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<tr>
<td>containerField is the field-label prefix indicating relationship to parent node. Examples: geometry Box, children Group, proxy Shape. containerField attribute is only supported in XML encoding of X3D scenes.</td>
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</table>

### class

<table>
<thead>
<tr>
<th>Description</th>
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<tbody>
<tr>
<td>[class CDATA #IMPLIED]</td>
</tr>
<tr>
<td>class is a space-separated list of classes, reserved for use by XML stylesheets. class attribute is only supported in XML encoding of X3D scenes.</td>
</tr>
</tbody>
</table>
CylinderSensor node

CylinderSensor converts x-y dragging motion by the pointing device into rotation about an axis

- 2-tuple motion converted to 4-tuple SFRotation
- Rotation restricted to local coordinate frame y-axis

Activated by peer geometry in scene graph

- Sensor itself is not rendered, unless sensed shape is itself cylindrical

Rotation output values can follow a ROUTE connection to parent Transform rotation

- Or connect to another SFRotation field elsewhere
CylinderSensor *diskAngle* and select point determines tracking mode

User selects either end or side of drag cylinder

- *diskAngle* measures from axis to touch point
- Thus can adjust sensor to match cylindrical shape approximation

- Bearing angle is measured from axis to user's track point
CylinderSensor fields, events

- Sends `isActive` true event when selected
- Sends `isActive` false event when deselected
- `minAngle, maxAngle` constrain the allowed rotation
  - default values do need adjustment, always use radians
  - Example: `minAngle='-3.14159' maxAngle='-3.14159'`
- `offset` holds latest (or initial) rotation value
- `autoOffset='true'` remembers prior rotation prior to resuming a new drag selection, otherwise `autoOffset='false'` jumps to restart at initial rotation
- `rotation_changed` and `trackPoint_changed` are the basic output events for sensor results
CylinderSensor off-axis rotation design pattern 1

CylinderSensor rotates about the Y axis of local coordinate frame
  • No internal field provided for offsetting that axis
  • Making rotation axis different than peer sensed geometry can be tricky

Following scene-graph design pattern shows how to rotate CylinderSensor about a different axis
  • First rotate to desired axis, CylinderSensor is child
  • Nest a second Transform rotation restoring original Y-axis, place sensed geometry here as child
CylinderSensor off-axis rotation design pattern 2

Scene

Viewpoint: description: CylinderSensor design pattern in action

Initial transform provides rotation offset for CylinderSensor axis

Transform: DEF: RotateCylinderSensorAxis, rotation: 0 0 1 -0.78

CylinderSensor: DEF: ObjectRotationSensor, description: click and drag to rotate

Transform: DEF: SensorRotationTransform

ROUTE: fromNode: ObjectRotationSensor, fromField: rotation_changed, toNode: SensorRotationTransform, toField: set_rotation

The following semi-transparent cylinder helps to illustrate the action of the CylinderSensor, and also makes it easier for a user to grab onto the target geometry being rotated.

Shape

Cylinder: height: 0.5, radius: 1

Appearance

set transparency="1" to hide completely

Material: diffuseColor: 0.8 0.8 0.8, transparency: 0.5

The following Transform gets a rotation opposite to RotateCylinderSensorAxis, restoring the original coordinate frame.

Transform: DEF: RestoreOriginalAxis, rotation: 0 0 1 0.78

The following subgraph is the target object being rotated

Shape

Box: size: 1 3 1

Appearance

Transform: scale: 3 3 3

Inline: DEF: CoordinateAxesVrml, url: "CoordinateAxes.wrl" ...
### CylinderSensor

CylinderSensor converts pointer motion (for example, a mouse or wand) into rotation values using an invisible cylinder aligned with local Y-axis.

**Hint:** Sensors are affected by peer nodes and children of peers.
**Hint:** Add transparent geometry to see the effect of the sensor.
**Hint:** initial relative bearing of pointer drag determines whether cylinder sides or end-cap disks are used for manipulation.

**DEF**

```
[DEF ID #IMPLIED]
DEF defines a unique ID name for this node, referencable by other nodes.
Hint: descriptive DEF names improve clarity and help document a model.
```

**USE**

```
[USE IDREF #IMPLIED]
USE means reuse an already DEF-ed node ID, ignoring _all_ other attributes and children.
Hint: USEing other geometry (instead of duplicating nodes) can improve performance.
Warning: do NOT include DEF (or any other attribute values) when using a USE attribute!
```

**Description**

```
[description: accessType inputOutput, type SFFloat CDATA #IMPLIED]
Text description to be displayed for action of this node.
Hint: use spaces, make descriptions clear and readable.
Hint: many XML tools substitute XML character references automatically if needed (like &#38; for & or &#34; for ").
```

**enabled**

```
[enabled: accessType inputOutput, type SFBool (true|false) "true"]
Enables/disables node operation.
```

**minAngle**

```
[minAngle: accessType inputOutput, type SFFloat CDATA "0"]
clamps rotation_changed events within range of min/max values
Hint: if minAngle > maxAngle, rotation is not clamped.
```

**maxAngle**

```
[maxAngle: accessType inputOutput, type SFFloat CDATA "0"]
clamps rotation_changed events within range of min/max values
Hint: if minAngle > maxAngle, rotation is not clamped.
```

**diskAngle**

```
[diskAngle: accessType inputOutput, type SFFloat CDATA "0.262" (15 degrees)]
Help decide rotation behavior from initial relative bearing of pointer drag: acute angle whether cylinder sides or end-cap disks of virtual-geometry sensor are used for manipulation.
Hint: diskAngle 0 forces disk-like behavior, diskAngle 1.57 (90 degrees) forces cylinder-like behavior.
```

**autoOffset**

```
[autoOffset: accessType inputOutput, type SFBool (true|false) "true"]
determines whether previous offset values are remembered/accumulated.
```

**offset**

```
[offset: accessType inputOutput, type SFFloat CDATA "0"]
Sends event and remembers last value sensed.
```

**isActive**

```
[isActive: accessType outputOnly, type SFBool (true|false) #FIXED ""]
isActive true/false events are sent when the sensor. isActive=true when primary mouse button is pressed, isActive=false when released.
```

**isOver**

```
[isOver: accessType outputOnly, type SFBool (true|false) #FIXED ""]
is pointing device over sensor's geometry?
```

**rotation_changed**

```
[rotation_changed: accessType outputOnly, type SFRotation CDATA #FIXED ""]
rotation_changed events equal sum of relative bearing changes plus offset value about Y-axis in local coordinate system.
```

**trackPoint_changed**

```
[trackPoint_changed: accessType outputOnly, type SFVec3f CDATA #FIXED ""]
trackPoint_changed events give intersection point of bearing with sensor's virtual geometry.
```

**containerField**

```
[containerField: NM_TOKEN "children"]
containerField is the field-label prefix indicating relationship to parent node. Examples: geometry Box, children Group, proxy Shape. containerField attribute is only supported in XML encoding of X3D scenes.
```

**class**

```
[class CDATA #IMPLIED]
class is a space-separated list of classes, reserved for use by XML stylesheets. class attribute is only supported in XML encoding of X3D scenes.
```
SphereSensor node

SphereSensor converts x-y dragging motion by the pointing device into an arbitration rotation

- 2-tuple motion converted to 4-tuple SFRotation
- Rotation about origin of local coordinate frame

Activated by peer geometry in scene graph

- Sensor itself is not rendered, unless corresponding sensed shape itself happens to be spherical

Rotation output values can have ROUTE connection to parent Transform rotation field

- Or connected to another SFRotation field elsewhere
SphereSensor fields, events

- Sends `isActive` true event when selected
- Sends `isActive` false event when deselected
- `offset` holds latest (or initial) rotation value
- `autoOffset='true'` remembers prior rotation prior to resuming a new drag selection, otherwise `autoOffset='false'` jumps to restart at initial rotation
- `rotation_changed` and `trackPoint_changed` are the basic output events for sensor results

As with all sensors, includes `description, enabled`
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<th>Property</th>
<th>Description</th>
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<td>DEF</td>
<td>Defines a unique ID name for this node, referencable by other nodes. Hint: descriptive DEF names improve clarity and help document a model.</td>
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</tr>
<tr>
<td>enabled</td>
<td>Enables/disables node operation.</td>
</tr>
<tr>
<td>autoOffset</td>
<td>Determines whether previous offset values are remembered/accumulated.</td>
</tr>
<tr>
<td>offset</td>
<td>Sends event and remembers last value sensed.</td>
</tr>
<tr>
<td>isActive</td>
<td>isActive true/false events are sent when triggering the sensor. isActive=true when primary mouse button is pressed, isActive=false when released.</td>
</tr>
<tr>
<td>isOver</td>
<td>isOver true/false events are sent when pointing device over sensor's geometry?</td>
</tr>
<tr>
<td>rotation_changed</td>
<td>rotation_changed events equal sum of relative bearing changes plus offset value.</td>
</tr>
<tr>
<td>trackPoint_changed</td>
<td>trackPoint_changed events give intersection point of bearing with sensor's virtual geometry.</td>
</tr>
<tr>
<td>containerField</td>
<td>containerField is the field-label prefix indicating relationship to parent node. Examples: geometry Box, children Group, proxy Shape. containerField attribute is only supported in XML encoding of X3D scenes.</td>
</tr>
<tr>
<td>class</td>
<td>class is a space-separated list of classes, reserved for use by XML stylesheets. class attribute is only supported in XML encoding of X3D scenes.</td>
</tr>
</tbody>
</table>
KeySensor node

KeySensor is a one-character-at-a-time interface, capturing key presses from user's keyboard

• Helpful for selecting from menu choices
• Helpful for creating a special keyboard-driven navigation interface
• Only gives key name, not precise shifted character

Control, alt, shift keys sent as separate events

• As are certain special “action keys”

Processing key events requires a Script node

• Covered in Chapter 9, Event Utilities and Scripting
KeySensor events 1

- Sends `isActive` true event when selected
- Sends `isActive` false event when deselected
- `keyPress, keyRelease` provide SFString value for the specific key pressed (or released)
  - Usually upper-case or primary key symbol only
- `shiftKey, altKey, controlKey` are SFBool binary values indicating whether keys were pressed or released

KeySensor also has `enabled` field

- but not `description` since display is challenging
**KeySensor events**

- `actionKeyPress`, `actionKeyRelease` provide `SFInt32` values when pressed or released

<table>
<thead>
<tr>
<th>Key</th>
<th>Value</th>
<th>Interaction Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>F1–F12</td>
<td>1–12</td>
<td></td>
</tr>
<tr>
<td>Home</td>
<td>13</td>
<td>First viewpoint</td>
</tr>
<tr>
<td>End</td>
<td>14</td>
<td>Last viewpoint</td>
</tr>
<tr>
<td>PageUp</td>
<td>15</td>
<td>Prior viewpoint</td>
</tr>
<tr>
<td>PageDown</td>
<td>16</td>
<td>Next viewpoint</td>
</tr>
<tr>
<td>Arrow up</td>
<td>17</td>
<td>Cursor up</td>
</tr>
<tr>
<td>Arrow down</td>
<td>18</td>
<td>Cursor down</td>
</tr>
<tr>
<td>Arrow left</td>
<td>19</td>
<td>Cursor left</td>
</tr>
<tr>
<td>Arrow right</td>
<td>20</td>
<td>Cursor right</td>
</tr>
</tbody>
</table>
function keyPress (value) {
    Browser.print ('Key press = ' + value + '. Initial pointer: ' + ptr + '\n');
    // bind next viewpoint
    if (value == 'N' || value == 'n') {
        ptr ++;
        if (ptr > 5) {
            ptr = 1;
        }
        if (ptr == 1) {
            bind_View1 = true;
        }
        if (ptr == 2) {
            bind_View2 = true;
        }
        if (ptr == 3) {
            bind_View3 = true;
        }
        if (ptr == 4) {
            bind_View4 = true;
        }
        if (ptr == 5) {
            bind_View5 = true;
        }
        if (ptr == 6) {
            bind_View6 = true;
        }
    }
    // similarly, bind previous viewpoint
    if (value == 'P' || value == 'p') {
        if (ptr == 1) {
            bind_View1 = false;
        }
        if (ptr == 2) {
            bind_View2 = false;
        }
        if (ptr == 3) {
            bind_View3 = false;
        }
        if (ptr == 4) {
            bind_View4 = false;
        }
        if (ptr == 5) {
            bind_View5 = false;
        }
        if (ptr == 6) {
            bind_View6 = false;
        }
    }
}
<table>
<thead>
<tr>
<th>KeySensor</th>
<th>KeySensor generates events as the user presses keys on the keyboard. Supports notion of &quot;keyboard focus&quot;.</th>
</tr>
</thead>
<tbody>
<tr>
<td>DEF</td>
<td>[DEF ID #IMPLIED] DEF defines a unique ID name for this node, referencable by other nodes. Hint: descriptive DEF names improve clarity and help document a model.</td>
</tr>
<tr>
<td>USE</td>
<td>[USE IDREF #IMPLIED] USE means reuse an already DEF-ed node ID, ignoring <em>all</em> other attributes and children. Hint: USEing other geometry (instead of duplicating nodes) can improve performance. Warning: do NOT include DEF (or any other attribute values) when using a USE attribute!</td>
</tr>
<tr>
<td>enabled</td>
<td>[enabled: accessType inputOutput, type SFBool (true</td>
</tr>
<tr>
<td>keyPress</td>
<td>[keyPress: accessType outputOnly, type SFSingle CDATA #IMPLIED] Events generated when user presses character-producing keys on keyboard produces integer UTF-8 character values.</td>
</tr>
<tr>
<td>keyRelease</td>
<td>[keyRelease: accessType outputOnly, type SFSingle CDATA #IMPLIED] Events generated when user releases character-producing keys on keyboard produces integer UTF-8 character values.</td>
</tr>
<tr>
<td>actionKeyPress</td>
<td>[actionKeyPress: accessType outputOnly, type SFInt32 CDATA #IMPLIED] action key press gives following values: HOME=000 END=1001 PGUP=1002 PGDN=1003 UP=1004 DOWN=1005 LEFT=1006 RIGHT=1007 F1..F12 = 1008..1019.</td>
</tr>
<tr>
<td>actionKeyRelease</td>
<td>[actionKeyRelease: accessType outputOnly, type SFInt32 CDATA #IMPLIED] action key release gives following values: HOME=000 END=1001 PGUP=1002 PGDN=1003 UP=1004 DOWN=1005 LEFT=1006 RIGHT=1007 F1..F12 = 1008..1019.</td>
</tr>
<tr>
<td>shiftKey</td>
<td>[shiftKey: accessType outputOnly, type SFBool (true</td>
</tr>
<tr>
<td>controlKey</td>
<td>[controlKey: accessType outputOnly, type SFBool (true</td>
</tr>
<tr>
<td>altKey</td>
<td>[altKey: accessType outputOnly, type SFBool (true</td>
</tr>
<tr>
<td>isActive</td>
<td>[isActive: accessType outputOnly, type SFBool (true</td>
</tr>
<tr>
<td>containerField</td>
<td>[containerField: NMTOKEN &quot;children&quot;] containerField is the field-label prefix indicating relationship to parent node. Examples: geometry Box, children Group, proxy Shape. containerField attribute is only supported in XML encoding of X3D scenes.</td>
</tr>
<tr>
<td>class</td>
<td>[class CDATA #IMPLIED] class is a space-separated list of classes, reserved for use by XML stylesheets. class attribute is only supported in XML encoding of X3D scenes.</td>
</tr>
</tbody>
</table>
StringSensor node, events

StringSensor provides a string-based interface to the user's keyboard

• Each character key press is collected until <Enter> key is returned, completing finalText string
• Intermediate string results (including deletions) also available as user proceeds in enteredText string
• deletionAllowed is boolean field that enables <Backspace>, <Delete> keys

StringSensor has isActive events, enabled field
• but not description since display is challenging
<head>
<meta content='StringSensor.x3d' name='title'/>
<meta content='A StringSensor example that displays typed text in the world.' name='description'/>
<meta content='Leonard Daly and Don Brutzman' name='creator'/>
<meta content='7 June 2006' name='created'/>
<meta content='10 February 2008' name='modified'/>
<meta content='http://X3DGraphics.com' name='reference'/>
<meta content='Copyright (c) 2006, Daly Realism and Don Brutzman' name='rights'/>
<meta content='X3D book, X3D graphics, X3D-Edit, http://www.x3dgraphics.com' name='subject'/>
<meta content='X3D-Edit, https://savage.nps.edu/X3D-Edit' name='generator'/>
<meta content='.//license.html' name='license'/>
</head>

<Scene>
  <Background skyColor='1 1 1'/>
  <Viewport description='Book View' position='-0.02 0.01 6.05'/>
  <StringSensor DEF='GenText' deletionAllowed='true' enabled='true'/>
</Scene>

<Transform translation='0 0 -1'>
  <Shape>
    <Appearance>
      <Material diffuseColor='1 1 0'/>
    </Appearance>
    <Box size='1 1 .1'/>
  </Shape>
</Transform>

<Transform translation='-3.8 0 0 0'>
  <Shape>
    <Appearance>
      <Material diffuseColor='0 0 1'/>
    </Appearance>
    <Text DEF='DisplayText'>
      <FontStyle justify="#BEGIN" #MIDDLE" size='0.75'/>
    </Text>
  </Shape>
</Transform>

<Script DEF='Converter' url='converter.js' http='true'>
  <field accessType='inputOnly' name='SFString_MFString' type='SFString'/>
  <field accessType='outputOnly' name='MFString_out' type='MFString'/>
</Script>

<ROUTE fromField='enteredText' fromNode='GenText' toField='SFString_MFString' toNode='Converter'/>
<ROUTE fromField='MFString_out' fromNode='Converter' toField='string' toNode='DisplayText'/>
</X3D>

Type text using StringSensor
// Description: Collection of various data-type conversion utility methods.
// filename: converter.js
// Author: Len Daly and Don Brutzman
// Identifier: http://X3dGraphics.com/examples/X3dForWebAuthors/Chapter08-UserInteractivity/converter.js
// Created: 17 June 2006
// Revised: 15 February 2008
// Reference: http://X3dGraphics.com/examples/X3dForWebAuthors/Chapter08-UserInteractivity/String2Sensor.x3d
// License: http://X3dGraphics.com/examples/X3dForWebAuthors/license.html

The name of a method indicates the incoming and outgoing datatypes.

If a particular element needs to be selected (e.g., SFVec3f to SFFloat), then
the element name is indicated after the incoming datatype (e.g., SFVec3fX means
the X ([0]) element of the datum.

Outgoing values (events) are always named after the datatype with '_out' appended.
If a particular element was selected, then the element name appears after the
underscore and before 'out'.

The exception to this naming convention is a conversion from MFz to SFz. In that
case, the first element ([0]) is always taken and no special notation is used.

function MFString_SFString (value) {
  SFString_out = value[0];
}

function SFString_MFString (value) {
  MFString_out = new MFString (value);
}

function SFVec3fX_SFFloat (value) {
  SFFloat_Xout = value[0];
}

function SFVec3fY_SFFloat (value) {
  SFFloat_Yout = value[1];
}

function SFVec3fZ_SFFloat (value) {
  SFFloat_Zout = value[2];
}
<table>
<thead>
<tr>
<th><strong>StringSensor</strong></th>
<th><strong>StringSensor generates events as the user presses keys on the keyboard.</strong></th>
</tr>
</thead>
</table>
| **DEF**          | [DEF ID #IMPLIED]  
DEF defines a unique ID name for this node, referencable by other nodes.  
**Hint:** descriptive DEF names improve clarity and help document a model. |
| **USE**          | [USE IDREF #IMPLIED]  
USE means reuse an already DEF-ed node ID, ignoring _all_ other attributes and children.  
**Hint:** USEing other geometry (instead of duplicating nodes) can improve performance.  
**Warning:** do NOT include DEF (or any other attribute values) when using a USE attribute! |
| **enabled**      | [enabled: accessType inputOutput, type SFBool (true|false) "true"]  
Enables/disables node operation. |
| **deletionAllowed** | [deletionAllowed: accessType inputOutput, type SFBool (true|false) "true"]  
If deletionAllowed is true, then previously entered character in enteredText can be removed. If deletionAllowed is false, then characters may only be added to the string.  
**Hint:** deletion key is typically defined by local system. |
| **isActive**    | [isActive: accessType outputOnly, type SFBool (true|false) #FIXED """"]  
isActive true/false events are sent when triggering the sensor. isActive=true when primary mouse button is pressed, isActive=false when released. |
| **enteredText** | [enteredText: accessType outputOnly, type SFString CDATA #FIXED """"]  
Events generated as character-producing keys are pressed on keyboard. |
| **finalText**   | [finalText: accessType outputOnly, type SFString CDATA #FIXED """"]  
Events generated when sequence of keystrokes matches keys in terminationText string when this condition occurs, enteredText is moved to finalText and enteredText is set to empty string.  
**Hint:** termination key is typically defined by local system. |
| **containerField** | [containerField: NMTOKEN "children"]  
containerField is the field-label prefix indicating relationship to parent node. Examples: geometry Box, children Group, proxy Shape. containerField attribute is only supported in XML encoding of X3D scenes. |
| **class**       | [class CDATA #IMPLIED]  
class is a space-separated list of classes, reserved for use by XML stylesheets. class attribute is only supported in XML encoding of X3D scenes. |
Example: user-interactivity sensor nodes

UserInteractivitySensorNodes.x3d

- Select (click and hold) TouchSensor Cone to alternate Background nodes
- Select and drag PlaneSensor -- Box on the screen
- Select and drag to rotate CylinderSensor -- Cylinder
- Select and drag to spin SphereSensor -- Sphere

Keyboard inputs are also activated

- KeySensor indicates keyPress
- StringSensor shows finalText once <Enter> pressed
- Console shows enteredText (includes deletes if any)
Sensor node examples

Touch Sensor
Plane Sensor
Cylinder Sensor
Sphere Sensor

? Press keys then <Enter>

Sensor node examples

Touch Sensor
Plane Sensor
Cylinder Sensor
Sphere Sensor

hello StringSensor!
<?xml version="1.0" encoding="UTF-8"?>
<!DOCTYPE X3D PUBLIC "ISO//Web3D//DTD X3D 3.1.1//EN" "http://www.web3d.org/specifications/x3d-3.1.dtd">
<meta content='SensorNodeExamples.x3d' name='title'/>
<meta content='A collection of all the user interactivity sensor nodes: TouchSensor, PlaceSensor, CylinderSensor, SphereSensor, KeySensor' name='description'/>
<meta content='Don Brutzman' name='creator'/>
<meta content='30 April 2005' name='created'/>
<meta content='16 February 2008' name='modified'/>
<meta content='Copyright 2006, Daily Realism and Don Brutzman' name='rights'/>
<meta content='http://X3DGraphics.com/examples/X3DForWebAuthors/Chapter08-UserInteractivity/UserInteractivitySensorNodes.x3d' name='identifier'/>
<meta content='X3D-Edit' https://savages.nps.edu/X3D-Edit' name='generator'/>
<meta content='licence.html' name='license'/>
</head>

<Scene>

<Viewpoint description='User interactivity sensor nodes' position='0 0 12'/>
<Background DEF='BackgroundDefault' groundColor='0.2 0.4 0.6' skyColor='0.2 0.4 0.6'/>
<Background DEF='BackgroundTouchCone' skyColor='0.5 0.7 0.9'/>
<Transform translation='0 4 0'>
  <Shape>
    <Text string='Sensor node examples' />
    <FontStyle justify='MIDDLE' size='1.5'/>
  </Text>
  <Appearance>
    <Material DEF='DefaultMaterial' diffuseColor='0.9 0.6 0.4'/>
  </Appearance>
  </Shape>
</Transform>
<Transform translation='0 1 0'>
  <Transform translation='-6 0 0'>
    <TouchSensor DEF='DefaultTouchSensor' description='click to activate TouchSensor bind alternate Background' enabled='true'>
      <Shape>
        <Cone />
        <Appearance>
          <Material diffuseColor='1 0.2 0.2'/>
        </Appearance>
      </Shape>
    </TouchSensor>
  </Transform>
</Transform>
<Transform translation='0 -2 0'>
  <Shape>
    <Text string='Touch Sensor' solid='false'>
      <FontStyle DEF='JustifyMiddle' justify='MIDDLE' size='MIDDLE'/>
    </Text>
    <Appearance USE='RedAppearance'/>
  </Shape>
</Transform>
</Scene>
<Shape>
  <Text DEF='KeyText' solid="false" string='?'>
  <FontStyle justify="Middle"/>
  </Text>
  <Appearance USE="BrownAppearance"/>
</Shape>
</Transform>
<Transform translation="-2 -3 0">
  <Shape>
    <Text DEF='StringText' solid="false" string='Press keys then &lt;Enter&gt;:'>
    <FontStyle justify="BEGIN" MIDDLE"/>
    </Text>
    </Appearance USE="BrownAppearance"/>
  </Shape>
</Transform>
<KeySensor DEF='DefaultKeySensor' enabled='true'/>
<StringSensor DEF='DefaultStringSensor' deletionAllowed='true' enabled='true'/>
<Script DEF='KeyboardProcessor'>
  <field name='keyInput' type='SFString' accessType='inputOnly'/>
  <field name='finalTextInput' type='SFString' accessType='inputOnly'/>
  <field name='enteredTextInput' type='SFString' accessType='inputOnly'/>
  <field name='keyOutput' type='MFString' accessType='outputOnly'/>
  <field name='stringOutput' type='MFString' accessType='outputOnly'/>
  <![CDATA[
    ecmscript:
    function keyInput (inputValue) {
      Browser.print ('KeyInput=' + inputValue + '\n'); // console output
      keyOutput = new MFString (inputValue); // type conversion
    }
    function finalTextInput (inputValue) {
      Browser.print ('finalText=' + inputValue + '\n'); // console output
      stringOutput = new MFString (inputValue); // type conversion
    }
    function enteredTextInput (inputValue) {
      Browser.print ('enteredText=' + inputValue + '\n'); // console output
    }
  ]]>}
</Script>
<ROUTE fromNode='DefaultKeySensor' fromField='keyPress' toNode='KeyboardProcessor' toField='keyInput'/>
<ROUTE fromNode='DefaultStringSensor' fromField='finalText' toNode='KeyboardProcessor' toField='finalTextInput'/>
<ROUTE fromNode='DefaultStringSensor' fromField='enteredText' toNode='KeyboardProcessor' toField='enteredTextInput'/>
<ROUTE fromNode='KeyboardProcessor' fromField='keyOutput' toNode='KeyText' toField='string'/>
<ROUTE fromNode='KeyboardProcessor' fromField='stringOutput' toNode='StringText' toField='string'/>
Chapter Summary
Summary: User Interactivity

User interactivity is initiated via sensor nodes, which capture user inputs and are hooked up to provide appropriate responses:

- **TouchSensor** senses pointing device (mouse, etc.)
- **PlaneSensor** is a drag sensor that converts x-y pointer motion to move objects in a plane
- **CylinderSensor** and **SphereSensor** are drag sensors that convert x-y pointer motion to rotate objects
- **KeySensor** and **StringSensor** capture keyboard input

Interactivity sensors initiate animation chains
Suggested exercises

Illustrate and annotate ROUTE connections in an animation scene graph (documenting 10 steps)

• Print out one of these scenes in landscape mode, either using the X3dToXhtml.xslt stylesheet version or Netbeans-provided 'Save as HTML' option.
• Then draw all ROUTE connections, label beginning and end of each by name, type and accessType
• Best candidate: UserInteractivitySensorNodes.x3d

Draw animation chain diagrams to document behaviors in your own example scenes

• Add use-case summaries about user intent
Additional Resources
ArbitraryAxisCylinderSensor Prototype

ArbitraryAxisCylinderSensor is a prototype that simplifies the design pattern of aligning a CylinderSensor about an arbitrary axis

- https://savage.nps.edu/Savage/Tools/Animation
- Prototype definition: ArbitraryAxisCylinderSensorPrototype.x3d
- ProtoInstance examples: ArbitraryAxisCylinderSensorExamples.x3d

Fields match those of CylinderSensor, plus:

- shiftRotationAxis, center, children, plus show/scale/color/transparency of CylinderSensorShape
ArbitraryAxisCylinderSensor Examples
DoubleClickTouchSensor

DoubleClickTouchSensor is a prototype alternative to TouchSensor that detects when a user has rapidly selected an object twice

- https://savage.nps.edu/Savage/Tools/Animation
- Prototype definition: DoubleClickTouchSensorPrototype.x3d
- ProtoInstance examples: DoubleClickTouchSensorExample.x3d

Fields match those of TouchSensor, plus:
- \textit{maxDelayInterval} allowed for distinguishing between single and double click, in seconds
TimeDelaySensor Prototype

TimeDelaySensor is an alternative to TimeSensor that includes a time delay before firing

- https://savage.nps.edu/Savage/Tools/Animation
- Prototype definition: TimeDelaySensorPrototype.x3d
- ProtoInstance examples: TimeDelaySensorExample.x3d

Fields match those of TimeSensor, plus:

- `delayInterval`, `delayCompleteTime`
TimeSensorEaseInEaseOut Prototype

TimeSensorEaseInEaseOut is an alternative to TimeSensor with a slower ramp at beginning and end of a cycle, thus smoothing transitions

- [https://savage.nps.edu/Savage/Tools/Animation](https://savage.nps.edu/Savage/Tools/Animation)
- Prototype definition: TimeSensorEaseInEaseOutPrototype.x3d
- ProtoInstance examples: TimeSensorEaseInEaseOutExample.x3d

Fields match those of TimeSensor

- Slight linear slowdown for first and last 10%
- Slight linear speedup in between
1. click text to move Boxes: linear TimeSensor grey EaseInEaseOut red

2. click text to move Boxes: linear TimeSensor grey EaseInEaseOut red

3. click text to move Boxes: linear TimeSensor grey EaseInEaseOut red

4. click text to move Boxes: linear TimeSensor grey EaseInEaseOut red
References
References 1

**X3D: Extensible 3D Graphics for Web Authors**
by Don Brutzman and Leonard Daly, Morgan Kaufmann Publishers, April 2007, 468 pages.

- Chapter 8, User Interactivity
- http://x3dGraphics.com
- http://x3dgraphics.com/examples/X3dForWebAuthors

**X3D Resources**

- http://www.web3d.org/x3d/content/examples/X3dResources.html
References  2

X3D-Edit Authoring Tool
  • https://savage.nps.edu/X3D-Edit

X3D Scene Authoring Hints
  • http://x3dgraphics.com/examples/X3dSceneAuthoringHints.html

X3D Graphics Specification
  • http://www.web3d.org/x3d/specifications
  • Also available as help pages within X3D-Edit
References  3


- http://www.wiley.com/legacy/compbooks/vrml2sbk/cover/cover.htm
- http://www.web3d.org/x3d/content/examples/Vrml2.0Sourcebook
- Chapter 9 - Sensing Viewer


- http://www.manning.com/barrilleaux
References 4


- http://www.3dui.org


Conferences 1

ACM SIGGRAPH

• Special Interest Group on Graphics is the leading professional society for computer graphics and interactive techniques
• http://www.siggraph.org

ACM SIGCHI

• Special Interest Group on Computer-Human Interaction, brings together people working on the design, evaluation, implementation, and study of interactive computing systems for human use
• http://www.sigchi.org
Conferences 2

IEEE Symposium on 3D User Interfaces (3DUI)
  • http://conferences.computer.org/3dui

IEEE Symposium on Virtual Reality (VR)
  • http://conferences.computer.org/vr

Web3D Symposium
  • In cooperation with Web3D Consortium, ACM SIGGRAPH and Eurographics
  • http://www.web3d2009.org
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Listen to one of the first (and perhaps still greatest) country rock albums of all time by the Byrds: *Sweetheart of the Rodeo*, 1968. The cover is by Monterey California artist Jo Mora and was used for the Salinas Rodeo. “One Hundred Years from Now” is among Gram Parsons' best songs.

### One Hundred Years from Now by Gram Parsons

One hundred years from this day
Will the people still feel this way
Still say the things that they're saying right now?
Everyone said I'd hurt you
They said I'd desert you
If I go away, you know I'm gonna get back somehow

Nobody knows what kind of trouble we're in
Nobody seems to think it all might happen again

One hundred years from this time
Would anybody change their mind
And find out one thing or two about life?
But people are always talking
You know they're always talking
Everybody's so wrong that I know it's gonna work out right

It's fun to take the long view when thinking about X3D.
Contents

Chapter Overview

Concepts

X3D Nodes and Examples

Chapter Summary and Suggested Exercises

Additional Resources and References
Chapter Overview
Overview: User Interactivity

User interactivity is initiated via sensor nodes, which capture user inputs and are hooked up to provide appropriate responses

- TouchSensor senses pointing device (mouse, etc.)
- PlaneSensor is a drag sensor that converts x-y pointer motion to move objects in a plane
- CylinderSensor and SphereSensor are drag sensors that convert x-y pointer motion to rotate objects
- KeySensor and StringSensor capture keyboard input

Interactivity sensors initiate animation chains

Dragging is the movement of a selected object using the pointing device, a capability provided by the drag sensors.

Animation chains are covered in Chapter 7, Event Animation and Interpolation.
Related nodes

Chapter 4, Viewing and Navigation nodes
- Anchor: pointing device
  - Selects another Viewpoint or loads another scene
  - Show description when pointing device is over geometry
- Billboard rotates child geometry to face user
- Collision reports if viewer collides with geometry

Chapter 12, Environment Sensor and Sound
- LoadSensor reports when media asset is loaded
- ProximitySensor reports when user is in vicinity
- VisibilitySensor indicates when user's current camera view can see sensed geometry

User Interactivity nodes directly follow the event model presented in Chapter 7.
Concepts
Importance of user interaction

Animated scenes are more interesting than static unchanging geometry

X3D interaction consists of sensing user actions and then prompting appropriate responses

Scenes that include behaviors which respond to user direction and control are more lively

Freedom of navigation and interaction contribute to user's sense of presence and immersion

Thus animation behaviors tend to be reactive and declarative, responding to the user

There is a large body of work in 3D user interaction. See the Additional Resources section.
Sensors produce events

Sensors detect various kinds of user interaction and produce events to ROUTE within a scene

- Each sensor detects a certain kind of interaction, then produces one or more events

Authors decide how the events describing user interaction are interpreted and handled

- This approach allows great flexibility for authors

TODO Add route diagram here...
Using sensors in a scene

Three common design patterns (→ = ROUTE)

• Trigger (sensor) → Clock → Interpolator → Target node

• Sensor → Target node

• Sensor → Script (adaptor) → Target node

TODO add figure
Pointing devices

Pointing device is primary tool for user interaction with geometry in a scene

- Mouse, Touchpad, touchscreen, or tracking stylus
- Arrow, Enter, other keys are allowed substitutes
- Trackball, data glove, game controller
- Tracking wand or other device in immersive 3D environments (such as a cave)
- Eye trackers and other advanced devices possible

X3D sensors designed for use with any generic pointing device, thus making scenes portable

Very different from most programming approaches...
Sensed geometry intersection, selection

Pointing devices communicate user's intended direction, movement, and selection (if any)

- Browsers and viewers usually superimpose 2D icon to indicate user's intended pointing direction
- 2D overlay icon may change to indicate selection

Sensors react to corresponding sibling and child geometry in the scene graph

- Pointing at other geometry means sensor activation no longer possible
- Usually one sensor must be deactivated before another can become active
Common field: *enabled*

*enabled* is an input/output boolean field that turns a sensor node on or off

- Thus allowing author to permit or disable flow of user-driven events which drive other responses
- Set *enabled*='false' to disrupt an event chain

Regardless of whether *enabled*='true' a sensor still needs a ROUTE connection from its output, or else no interaction response occurs

For author: Get ready...
Common field: *isOver*

*isOver* is an [outputOnly](https://en.wikipedia.org/wiki/Output_only) boolean field that reports when pointing at sensed geometry

- *isOver* true value sent when pointer is over shapes
- *isOver* false value sent when pointer icon is no longer over shapes
- If selection occurred, *isOver* false doesn't occur until after selection is released

Routing *isOver* values can enable animation

- Rapid sequencing on/off might remain a difficulty
- Take care that animation doesn't move viewpoint or geometry out from under the pointing device

For user: Get set...
Common field: *isActive*

*isActive* is an `outputOnly` boolean field that reports when sensor has received user input

- *isActive* true value sent when selection begins
- *isActive* false value sent when selection released
- Note that *isActive* true already occurs as a prerequisite when a sensor is initially enabled

Routing *isActive* values can enable, disable TimeSensor and other animation nodes

- Rapid sequencing on/off can be a difficulty, however
- BooleanFilter, BooleanToggle, BooleanTrigger also useful: Chapter 9 Event Utilities and Scripting

For user: Go!!
Common field: *description*

Each sensor's *description* field alerts users to the presence and intended purpose of each sensor

- Thus including a *description* is quite important, otherwise user is left to guess about responses
- Nevertheless many authors forget to include *description*, which inhibits interactivity

X3D Specification gives browsers flexibility about how *description* strings are displayed

- Overlay text, window-border text, perhaps audio
Dragging

Dragging means to select (activate) a sensed object, then to move the pointing device while the sensor is still activated. This user action causes continuous generation of output events while dragging motion occurs:

• Click + drag + release = Select + hold + release

Several common fields

• enabled, description, isActive, isOver, touchTime

Three X3DDragSensorNode type sensors are

• CylinderSensor, PlaneSensor, SphereSensor
3D (6DOF) control using 2D devices

Selected objects are 3D, located in 3D space
  • Which provides 6 degrees of freedom (DOF) for 3D object motion, e.g. \((x, y, z, \text{roll}, \text{pitch}, \text{yaw})\)

However most pointing devices only 2D control, since only movements are left-right, up-down
  • Mouse, touchpad or touch screen, keyboard, etc.

Must map 2D output device to 3D/6DOF motions
  • Each drag sensor thus defines how 2D motion is interpreted: surface of cylinder, plane, or sphere
  • Hopefully authored in a manner intuitive to user

6DOF = six degrees of freedom, positional and rotational: \(x \ y \ z \ \text{roll} \ \text{pitch} \ \text{yaw}\)

Each of the dragging sensor nodes (CylinderSensor, PlaneSensor, SphereSensor) describe how they map 2D mouse motion (left-right, up-down) into 3D 6DOF space.
X3D Nodes and Examples
TouchSensor node

TouchSensor affects adjacent geometry, provides basic pointing-device contact interaction

- Sends *isOver* true event when first pointed at
- Sends *isActive* true event when selected
- Sends *isActive* false event when deselected
- Sends *isOver* false event when no longer pointed at

Selection is deliberate action by user, for example

- Mouse, touchpad, touchscreen: left-click button
- Keyboard: <Enter> key
- 3D wand: selection button

A change in pointer position is needed for TouchSensor to operate.

If the geometry or camera view is animated and the geometry moves out from under the pointer, no *isOver* false event is sent. The pointing-device cursor icon must be moved by the user off of the selected geometry in order to send an *isOver* false event.

So following the initial *isOver*='true' then *isActive*='true' event pair shown on the slide, it is possible to have a slightly different order: *isOver*='false' then *isActive*='false' iff the user moves off of the selected geometry while still selected.
Sensed geometry grouping

All geometry that is a peer (or children of peers) of the TouchSensor nodes can be sensed.

Use a grouping node (Group, Transform, etc.) to isolate sensed geometry of interest:
- Don't want to make entire scene selectable, otherwise interaction isn't very sophisticated.

Can attach different sensors to self-explanatory geometry for different tasks. Examples:
- Light switch `isOver` gives name, click to change.
- Billboarded Text or buttons for multiple controls.

The Group node is an excellent way to isolate the effectiveness of a sensor to only be affected by a certain set of nodes.
Sensed geometry grouping

Separate sensed geometry from other shapes by using grouping nodes

Next slide shows example excerpt
- Chapter04-ViewingNavigation/BindOperations.x3d

Scene structure for this example
- Viewpoints consuming, producing events
- Display geometry, no sensor peer
- Selectable geometry, TouchSensor peer
- Regular animation design pattern: TimeSensor, Interpolator, target Script node, ROUTE connections
Multiple TouchSensor nodes

Cannot sense just one part of grouped geometry

• Unless split out as separate groups of geometry, then Transform-ed to look like single shape to user

Can use multiple TouchSensor nodes, ROUTEs and event chains to accomplish multiple tasks

Can DEF, USE copies of single TouchSensor node, allowing multiple shapes to trigger same action

If multiple TouchSensor nodes at same level or above a given piece of geometry, nearest wins

• If tied at same distance, both activated at once

Note that multiple independent TouchSensor nodes are not the same as a simultaneous multiple-touch sensor capability.

Currently X3D does not have any multi-touch (multi-hand gesture) nodes defined. Nevertheless this remains an active area of research.

• The InstantReality X3D viewer team has successfully designed and implemented multi-touch sensor capabilities. This is experimental work.

• http://instantreality.de/documentation/nodetype

• http://instantreality.de/documentation/nodetype/MultiTouchNavigator
output event \textit{touchTime}

\textit{touchTime} sends an SFTime output event whenever sensed geometry is deselected

- Sent simultaneously with \textit{isActive} false event

Three prerequisites must be met for \textit{touchTime}:

1. Pointing device begins pointing at sensed geometry (generating \textit{isOver} true event)
2. Pointing device is initially activated by user selection (generating \textit{isActive} true event)
3. Pointing device is subsequently deactivated while still pointing at the sensed geometry (generating \textit{isActive} false event)

Because \textit{isActive} false and \textit{touchTime} events are sent simultaneously after meeting the same user-interaction preconditions, it is convenient to use

- \textit{isActive} for destination fields that need boolean inputs (such as a sensor's \textit{enabled} field)
- \textit{touchTime} for destination fields that need SFTime inputs (such as a TimeSensor node's \textit{set\_startTime} field)

It is good design that requires a user to keep the pointer on the selected geometry before deselecting and generating a \textit{touchTime} event. This allows a user to change their mind after initial (\textit{isActive} true) selection, by moving the pointer off of the sensed geometry before releasing the selection. Example sequence of events:

- User selects some sensed object with pointing device
- \textit{isActive} true event sent
- User decides that selecting the object is not desirable, and so moves the pointer off of the object before deselecting
- \textit{isActive} false event is still sent, but no corresponding \textit{touchTime} event is sent

As we shall see, it is possible to create event-animation logic that takes advantage of this difference.
Output events *hitPoint_changed*, *hitNormal_changed*, *hitTexCoord_changed*

**hitPoint_changed**
- sends output SFVec3f event providing 3D location coordinates of selection point, referenced to local coordinate system

**hitNormal_changed**
- sends output SFVec3f event providing normal vector of underlying geometry at selection point

**hitTexCoord_changed**
- sends output SFVec2f event providing 2D \((u, v)\) coordinates of underlying texture at selection point

The local coordinate system is determined by the combined translation, rotation and scaling effects of the Transform nodes that are parent nodes for the geometry of interest. This is often referred to as the transformation hierarchy.

Normal vectors are similarly pointing in a direction that is relative to the local coordinate system.

Texture coordinates are independent of the local coordinate system, only referring to \((u, v)\) coordinate values which range from 0 to 1 along each axis of a texture image. Texture coordinates are described in Chapter 5, Appearance Material and Textures.
Figure 8.2, page 230, *X3D for Web Authors*

http://X3dGraphics.com/examples/X3dForWebAuthors/Chapter08-UserInteractivity.TouchSensorPumpHouse.x3d
Example: opening doors

Interaction in 3D scenes doesn’t always have to be literal. It is easier to click on a door to open it, rather than turning a door knob.

Next example compares TouchSensor selections

- Left door opens on initial selection (click)
- Right door opens on later deselection (unclick)

Key difference: `isActive` is first true, then false

- To fix: routing events through a BooleanFilter and TimeTrigger can initiate TimeSensor appropriately
- These are Event Utility nodes, covered in Chapter 9
Chapter 8 - User Interactivity

http://X3dGraphics.com/examples/X3dForWebAuthors/Chapter08-UserInteractivity/Doors.x3d

The following snapshots show animation results after clicking on (selecting) each door.
TouchSensor tooltips

http://www.web3d.org/x3d/content/X3dTooltips.html#TouchSensor
PlaneSensor node

PlaneSensor converts x-y dragging motion by the pointing device into lateral translation in plane

- 2-tuple motion converted to 3-tuple SFVec3f
- Motion is parallel to local z=0 plane (screen plane)

Activated by peer geometry in scene graph

- Sensor itself is not rendered, unless background geometry or sensed shape itself has a planar side

Translation output values can follow a ROUTE connection to parent Transform translation

- Or connect to another SFVec3f field elsewhere
PlaneSensor fields, events

- Sends isActive true event when selected
- Sends isActive false event when deselected
- minPosition, maxPosition constrain X-Y translation to allowed planar region, defined as SFVec2f values
  - Example: minPosition='-2 -2' maxPosition='2 2'
- offset holds latest (or initial) SFVec3f position value
- autoOffset='true' remembers prior translation prior to resuming a new drag selection, otherwise autoOffset='false' jumps, restarts at initial position
- translation_changed and trackPoint_changed are the basic output events for sensor results

Default values minPosition='0 0' maxPosition='1 -1' are contradictory (minimum values are greater than corresponding maximum values), which results in the PlaneSensor being unconstrained.

These constraints are helpful for guiding the user to make reasonable adjustments, rather than dragging something off into the far distance somewhere.

Pay close attention to user viewpoint and perspective across the full range of possible movement, so that dragged geometry remains visible and accessible for further adjustment.

Linear movement can be achieved by setting either the min/max X or else min/max Z constraints to the same value. This is done in the next example, PlaneSensorPumpHouse.x3d.

As with all sensors, PlaneSensor includes description and enabled fields.
Figure 8.3, page 233, X3D for Web Authors

http://X3dGraphics.com/examples/X3dForWebAuthors/Chapter08-UserInteractivity/PlaneSensorPumpHouse.x3d
http://www.web3d.org/x3d/content/X3dTooltips.html#PlaneSensor
CylinderSensor node

CylinderSensor converts x-y dragging motion by the pointing device into rotation about an axis
• 2-tuple motion converted to 4-tuple SFRotation
• Rotation restricted to local coordinate frame y-axis

Activated by peer geometry in scene graph
• Sensor itself is not rendered, unless sensed shape is itself cylindrical

Rotation output values can follow a ROUTE connection to parent Transform *rotation*
• Or connect to another SFRotation field elsewhere

PlaneSensor gets from X-Y values to X-Y-Z values by simply holding Z to equal 0.
CylinderSensor $diskAngle$ and select point determines tracking mode

User selects either end or side of drag cylinder

- $diskAngle$ measures from axis to touch point
- Thus can adjust sensor to match cylindrical shape approximation

- Bearing angle is measured from axis to user’s track point

Figure 8.4, p. 236, X3D for Web Authors

User selection with pointing device defines the track point. The vector angle of the track point relative to the $diskAngle$ parameter determines whether CylinderSensor responds in end-cap tracking mode, or cylinder-wall tracking mode.

Each mode has a slightly different way of responding to user dragging motions, making response more intuitive if there is a good match to the geometry.

CylinderSensor can be forced to always operate in end-cap mode by setting $diskAngle$='1.5707' ($\pi/2$ radians), which is useful to emulate turning of knobs.

CylinderSensor can be forced to always operate in cylinder-wall sides mode by setting $diskAngle$='0' which is useful to emulate a thumbwheel rotation.

Angle relationships are measured as SFFloat radian values, while node output field $rotation\_changed$ is SFRotation.

The cylinder shown in the above diagram is typically invisible and describes the mathematical model of the sensor response. If the actual sensed geometry is not particularly cylindrical in shape, sometimes superimposing a semitransparent cylinder can make the reaction more obvious. For example prototypes, see

https://savage.nps.edu/Savage/Tools/Animation/ArbitraryAxisCylinderSensorExamples.x3d
CylinderSensor fields, events

- Sends isActive true event when selected
- Sends isActive false event when deselected
- minAngle, maxAngle constrain the allowed rotation
  - default values do need adjustment, always use radians
  - Example: minAngle='-3.14159' maxAngle='-3.14159'
- offset holds latest (or initial) rotation value
- autoOffset='true' remembers prior rotation prior to resuming a new drag selection, otherwise autoOffset='false' jumps to restart at initial rotation
- rotation_changed and trackPoint_changed are the basic output events for sensor results

As with all sensors, CylinderSensor includes description and enabled fields.
CylinderSensor off-axis rotation design pattern 1

CylinderSensor rotates about the Y axis of local coordinate frame
- No internal field provided for offsetting that axis
- Making rotation axis different than peer sensed geometry can be tricky

Following scene-graph design pattern shows how to rotate CylinderSensor about a different axis
- First rotate to desired axis, CylinderSensor is child
- Nest a second Transform rotation restoring original Y-axis, place sensed geometry here as child

This pattern works because a Sensor node acts upon all of its peers, and all of its peers' children.

Essentially both CylinderSensor and geometry are rotated to the new angle of interest, than the geometry is rotated back to its original orientation.
CylinderSensor off-axis rotation design pattern 2

Figure 8.6, p. 238, X3D for Web Authors

Note that the CylinderSensor is nested within the animated Transform, making the rotation changes an interesting feedback loop.
Figure 8.5, p. 237, *X3D for Web Authors*

http://X3dGraphics.com/examples/X3dForWebAuthors/Chapter08-UserInteractivity/CylinderSensorPumpHouse.x3d
http://www.web3d.org/x3d/content/X3dToolTips.html#CylinderSensor
SphereSensor node

SphereSensor converts x-y dragging motion by the pointing device into an arbitration rotation

- 2-tuple motion converted to 4-tuple SFRotation
- Rotation about origin of local coordinate frame

Activated by peer geometry in scene graph

- Sensor itself is not rendered, unless corresponding sensed shape itself happens to be spherical

Rotation output values can have ROUTE connection to parent Transform rotation field

- Or connected to another SFRotation field elsewhere
SphereSensor fields, events

- Sends `isActive` true event when selected
- Sends `isActive` false event when deselected
- `offset` holds latest (or initial) rotation value
- `autoOffset='true'` remembers prior rotation prior to resuming a new drag selection, otherwise `autoOffset='false'` jumps to restart at initial rotation
- `rotation_changed` and `trackPoint_changed` are the basic output events for sensor results

As with all sensors, includes `description`, `enabled`
Figure 8.7, p. 241, *X3D for Web Authors*

http://X3dGraphics.com/examples/X3dForWebAuthors/Chapter08-UserInteractivity/SphereSensor-Lefty.x3d
http://www.web3d.org/x3d/content/X3dTooltips.html#SphereSensor
KeySensor node

KeySensor is a one-character-at-a-time interface, capturing key presses from user's keyboard

- Helpful for selecting from menu choices
- Helpful for creating a special keyboard-driven navigation interface
- Only gives key name, not precise shifted character

Control, alt, shift keys sent as separate events

- As are certain special “action keys”

Processing key events requires a Script node

- Covered in Chapter 9, Event Utilities and Scripting
KeySensor events

- Sends `isActive` true event when selected
- Sends `isActive` false event when deselected
- `keyPress`, `keyRelease` provide SFString value for the specific key pressed (or released)
  - Usually upper-case or primary key symbol only
- `shiftKey`, `altKey`, `controlKey` are SFBool binary values indicating whether keys were pressed or released

KeySensor also has `enabled` field
- but not `description` since display is challenging

KeySensor includes `description` and `enabled` fields.
KeySensor events  2

- `actionKeyPress`, `actionKeyRelease` provide SFInt32 values when pressed or released

Table 8.15, page 243, *X3D for Web Authors*

Be careful not to unintentionally override default navigation behaviors for above keys.
Figure 8.8, page 244, *X3D for Web Authors*

http://X3dGraphics.com/examples/X3dForWebAuthors/Chapter08-UserInteractivity/KeySensor-Lefty.x3d
keySensor.js is invoked by a Script node in KeySensor-Lefty.x3d in order to process user key presses and output viewpoint binding events.

Script nodes are covered in Chapter 9, Event Utilities and Scripting.
http://www.web3d.org/x3d/content/X3dTooltips.html#KeySensor
StringSensor node, events

StringSensor provides a string-based interface to the user's keyboard

- Each character key press is collected until <Enter> key is returned, completing `finalText` string
- Intermediate string results (including deletions) also available as user proceeds in `enteredText` string
- `deletionAllowed` is boolean field that enables <Backspace>, <Delete> keys

StringSensor has `isActive` events, `enabled` field
- but not `description` since display is challenging

If displaying entered text, you may want to provide a colored Box background behind it in order to improve contrast and readability without clutter from the surrounding scene.
Figure 8.9, page 246, X3D for Web Authors

http://X3dGraphics.com/examples/X3dForWebAuthors/Chapter08-UserInteractivity/StringSensor.x3d
converter.js is invoked by a Script node in StringSensor.x3d in order to use the following type-conversion function:

```javascript
function SFString_MFString (value) {
    MFString_out = new MFString (value);
}
```

This script is necessary to convert the SFString output of the StringSensor node `enteredText` field into the MFString input needed for the Text node `string` field. In other words, a single SFString is converted into a MFString array with a single element.

Script nodes are covered in Chapter 9, Event Utilities and Scripting.
### StringSensor

**StringSensor** generates events as the user presses keys on the keyboard.

<table>
<thead>
<tr>
<th><strong>field</strong></th>
<th><strong>description</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>DEF</strong></td>
<td></td>
</tr>
<tr>
<td><strong>USE</strong></td>
<td></td>
</tr>
<tr>
<td><strong>enabled</strong></td>
<td></td>
</tr>
<tr>
<td><strong>deletionAllowed</strong></td>
<td></td>
</tr>
<tr>
<td><strong>isActive</strong></td>
<td></td>
</tr>
<tr>
<td><strong>enteredText</strong></td>
<td></td>
</tr>
<tr>
<td><strong>finalText</strong></td>
<td></td>
</tr>
<tr>
<td><strong>containerField</strong></td>
<td></td>
</tr>
<tr>
<td><strong>class</strong></td>
<td></td>
</tr>
</tbody>
</table>

---

[http://www.web3d.org/x3d/content/X3dToolips.html#StringSensor](http://www.web3d.org/x3d/content/X3dToolips.html#StringSensor)
Example: user-interactivity sensor nodes

UserInteractivitySensorNodes.x3d

- Select (click and hold) TouchSensor Cone to alternate Background nodes
- Select and drag PlaneSensor -- Box on the screen
- Select and drag to rotate CylinderSensor -- Cylinder
- Select and drag to spin SphereSensor -- Sphere

Keyboard inputs are also activated
- KeySensor indicates keyPress
- StringSensor shows finalText once <Enter> pressed
- Console shows enteredText (includes deletes if any)

http://X3dGraphics.com/examples/X3dForWebAuthors/Chapter08-UserInteractivity/UserInteractivitySensorNodes.x3d
The top screen is the initial view. Click and hold to select the Cone TouchSensor that binds the light-blue Background. Releasing unbinds that Background, restoring the original.

PlaneSensor, CylinderSensor and SphereSensor can each be selected and dragged. Their output values (SFVec3f, SFRotation, SFRotation) have ROUTE connections to either translate or rotate the respective parent Transform node.

Default KeySensor output text is a ? question mark. Note that the key output shows only a capital-letter character (or the primary character) for the key being pressed.

Default StringSensor output text is 'Press keys then <Enter>' - be patient since the finalText field doesn't send an output string until the <Enter> key is pressed.

The console shows the enteredText, as it is typed key by key, including <Backspace> or <Delete> effects (if any).

```plaintext
enteredText=H  enteredText=Hello String
enteredText=He  enteredText=Hello String
enteredText=Hel  enteredText=Hello StringS
enteredText=Hell  enteredText=Hello StringSe
enteredText=Hello  enteredText=Hello StringSen
enteredText=Hello S  enteredText=Hello StringSens
enteredText=Hello St  enteredText=Hello StringSensor
enteredText=Hello Str  enteredText=Hello StringSensor!
enteredText=Hello Strat  enteredText=Hello StringSensor!
```
http://X3dGraphics.com/examples/X3dForWebAuthors/Chapter08-UserInteractivity/UserInteractivitySensorNodes.x3d
Note that a Script node is needed to convert the SFString outputs of the KeySensor and TouchSensor into MFString inputs for the appropriate Text node string field.

This is one of the few remaining cases in X3D where a Script node is needed for data type conversion between a sensor output node and another X3D target node.
Chapter Summary
Summary: User Interactivity

User interactivity is initiated via sensor nodes, which capture user inputs and are hooked up to provide appropriate responses

- TouchSensor senses pointing device (mouse, etc.)
- PlaneSensor is a drag sensor that converts x-y pointer motion to move objects in a plane
- CylinderSensor and SphereSensor are drag sensors that convert x-y pointer motion to rotate objects
- KeySensor and StringSensor capture keyboard input

Interactivity sensors initiate animation chains

Dragging is the movement of a selected object using the pointing device, a capability provided by the drag sensors.

Animation chains are covered in Chapter 7, Event Animation and Interpolation.
Suggested exercises

Illustrate and annotate ROUTE connections in an animation scene graph (documenting 10 steps)

- Print out one of these scenes in landscape mode, either using the X3dToXhtml.xslt stylesheet version or Netbeans-provided 'Save as HTML' option.
- Then draw all ROUTE connections, label beginning and end of each by name, type and accessType
- Best candidate: UserInteractivitySensorNodes.x3d

Draw animation chain diagrams to document behaviors in your own example scenes

- Add use-case summaries about user intent

Someday we hope to automate the production of such diagrams.

X3dToXhtml.xslt is available via X3D-Edit menu X3D, Conversions
Additional Resources
ArbitraryAxisCylinderSensor Prototype

ArbitraryAxisCylinderSensor is a prototype that simplifies the design pattern of aligning a CylinderSensor about an arbitrary axis

- [https://savage.nps.edu/Savage/Tools/Animation](https://savage.nps.edu/Savage/Tools/Animation)
- Prototype definition: ArbitraryAxisCylinderSensorPrototype.x3d
- ProtoInstance examples: ArbitraryAxisCylinderSensorExamples.x3d

**Fields match those of CylinderSensor, plus:**

- `shiftRotationAxis`, `center`, `children`, plus `show/scale/color/transparency` of CylinderSensorShape

Prototypes are an extensibility mechanism to define new X3D nodes using existing X3D nodes. They are covered in Chapter 14.

**Warning:** ArbitraryAxisCylinderSensor operates on its children, NOT on its peers. This variation is necessary in order to accomplish the desired Transform rotation to a new orientation axis. Example use:

[https://savage.nps.edu/Savage/Tools/Animation/ArbitraryAxisCylinderSensorExamples.x3d](https://savage.nps.edu/Savage/Tools/Animation/ArbitraryAxisCylinderSensorExamples.x3d)

```xml
<ExternProtoDeclare name="ArbitraryAxisCylinderSensor">
    <!-- copy field definitions here -->
</ExternProtoDeclare>

<ProtoInstance name='ArbitraryAxisCylinderSensor' containerField='children'>
    <!-- rotate rotate CylinderSensor yAxis to xAxis -->
    <fieldValue name='shiftRotationAxis' value='0 0 1 -1.5707963'/>
    <fieldValue name='children'>
        <Shape>
            <Cylinder/>
            <Appearance>
                <Material diffuseColor='1 0 0'/>
            </Appearance>
        </Shape>
    </fieldValue>
</ProtoInstance>
```
These screen snapshots show the original unmanipulated scene above, and multiple user-rotated objects with different axis angles in the scene below.

https://savage.nps.edu/Savage/Tools/Animation/ArbitraryAxisCylinderSensorExamples.x3d
DoubleClickTouchSensor

DoubleClickTouchSensor is a prototype alternative to TouchSensor that detects when a user has rapidly selected an object twice

- https://savage.nps.edu/Savage/Tools/Animation
- Prototype definition: DoubleClickTouchSensorPrototype.x3d
- ProtoInstance examples: DoubleClickTouchSensorExample.x3d

Fields match those of TouchSensor, plus:

- `maxDelayInterval` allowed for distinguishing between single and double click, in seconds

Prototypes are an extensibility mechanism to define new X3D nodes using existing X3D nodes. They are covered in Chapter 14.

Example use:
https://savage.nps.edu/Savage/Tools/Animation/DoubleClickTouchSensorExample.x3d

```xml
<ExternProtoDeclare name="DoubleClickTouchSensor">
    <!-- copy field definitions here -->
</ExternProtoDeclare>

<ProtoInstance name='DoubleClickTouchSensor' DEF='TouchSensorActive'>
    <fieldValue name='description' value='double click to initiate time delay and color change'/>
    <fieldValue name='maxDelayInterval' value='0.5'/>
</ProtoInstance>
```
TimeDelaySensor Prototype

TimeDelaySensor is an alternative to TimeSensor that includes a time delay before firing

- [https://savage.nps.edu/Savage/Tools/Animation](https://savage.nps.edu/Savage/Tools/Animation)
- Prototype definition:
  TimeDelaySensorPrototype.x3d
- ProtoInstance examples:
  TimeDelaySensorExample.x3d

Fields match those of TimeSensor, plus:
- delayInterval, delayCompleteTime

Prototypes are an extensibility mechanism to define new X3D nodes using existing X3D nodes. They are covered in Chapter 14.

Example use:

```xml
<ExternProtoDeclare name='TimeDelaySensor'
  url='"TimeDelaySensorPrototype.x3d#TimeDelaySensor"
  "https://savage.nps.edu/Savage/Tools/Animation/TimeDelaySensorPrototype.x3d #TimeDelaySensor"
  "https://savage.nps.edu/Savage/Tools/Animation/TimeDelaySensorPrototype.wrl#TimeDelaySensor"
  "https://savage.nps.edu/Savage/Tools/Animation/TimeDelaySensorExample.x3d"
>
  <field accessType='inputOutput' name='startTime' type='SFTime'/>
  <field accessType='inputOutput' name='enabled' type='SFBool'/>
  <field accessType='inputOutput' name='delayInterval' type='SFTime'/>
  <field accessType='outputOnly' name='delayCompleteTime' type='SFTime'/>
  <field accessType='initializeOnly' name='traceEnabled' type='SFBool'/>
</ExternProtoDeclare>

<ProtoInstance DEF='DelayTimer' name='TimeDelaySensor'>
  <fieldValue name='delayInterval' value='3'/>
  <fieldValue name='traceEnabled' value='true'/>
</ProtoInstance>
```
TimeSensorEaseInEaseOut Prototype

TimeSensorEaseInEaseOut is an alternative to TimeSensor with a slower ramp at beginning and end of a cycle, thus smoothing transitions

- https://savage.nps.edu/Savage/Tools/Animation
- Prototype definition: TimeSensorEaseInEaseOutPrototype.x3d
- ProtoInstance examples: TimeSensorEaseInEaseOutExample.x3d

Fields match those of TimeSensor

- Slight linear slowdown for first and last 10%
- Slight linear speedup in between

Prototypes are an extensibility mechanism to define new X3D nodes using existing X3D nodes. They are covered in Chapter 14.

Example use:
https://savage.nps.edu/Savage/Tools/Animation/TimeSensorEaseInEaseOutExample.x3d

```xml
<ExternProtoDeclare name='TimeSensorEaseInEaseOut'>
    <!-- need to copy url and field definitions here -->
</ExternProtoDeclare>

<ProtoInstance name='TimeSensorEaseInEaseOut' DEF='EasyClock'>
    <fieldValue name='cycleInterval' value='3'/>
</ProtoInstance>
```
Snapshots showing progression of a TimeSensorEaseInEaseOut animation.

Each box starts and stops at the same locations and also at the same times. The white TimeSensor box travels at a constant speed throughout.

The TimeSensorEaseInEaseOut orange box starts more slowly at the start, speeds up to pass the white box, then slows to finish identically. This can be a more graceful way to perform some animations.

https://savage.nps.edu/Savage/Tools/Animation/TimeSensorEaseInEaseOutExample.x3d
References
References 1

*X3D: Extensible 3D Graphics for Web Authors*
by Don Brutzman and Leonard Daly, Morgan Kaufmann Publishers, April 2007, 468 pages.

- Chapter 8, User Interactivity
- http://x3dGraphics.com
- http://x3dgraphics.com/examples/X3dForWebAuthors

X3D Resources

- http://www.web3d.org/x3d/content/examples/X3dResources.html
References 2

X3D-Edit Authoring Tool
  • https://savage.nps.edu/X3D-Edit

X3D Scene Authoring Hints
  • http://x3dgraphics.com/examples/X3dSceneAuthoringHints.html

X3D Graphics Specification
  • http://www.web3d.org/x3d/specifications
  • Also available as help pages within X3D-Edit
References

- http://www.wiley.com/legacy/compbooks/vrml2sbk/cover/cover.htm
- http://www.web3d.org/x3d/content/examples/Vrml2.0Sourcebook
- Chapter 9 - Sensing Viewer

- http://www.manning.com/barrilleaux
References 4

  • http://www.3dui.org
  • http://people.cs.vt.edu/~bowman/3dui.org/3D UI Book.html

Conferences 1

ACM SIGGRAPH
- Special Interest Group on Graphics is the leading professional society for computer graphics and interactive techniques
- http://www.siggraph.org

ACM SIGCHI
- Special Interest Group on Computer-Human Interaction, brings together people working on the design, evaluation, implementation, and study of interactive computing systems for human use
- http://www.sigchi.org
Conferences 2

IEEE Symposium on 3D User Interfaces (3DUI)
  • http://conferences.computer.org/3dui

IEEE Symposium on Virtual Reality (VR)
  • http://conferences.computer.org/vr

Web3D Symposium
  • In cooperation with Web3D Consortium, ACM SIGGRAPH and Eurographics
  • http://www.web3d2009.org
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Good references on open source:
